

MLFB-Ordering data

6SL3230-1YE54-0AF0



Client order no. : Order no. : Offer no. :

Remarks:

Item no. : Consignment no. :

Project :

Rated data		
Input		
Number of phases	3 AC	
Line voltage	380 480 V +10 % -20 %	
Line frequency	47 63 Hz	
Rated voltage	400V IEC	480V NEC
Rated current (LO)	482.00 A	471.00 A
Rated current (HO)	400.00 A	392.00 A
Output		
Number of phases	3 AC	
Rated voltage	400V IEC	480V NEC
Rated power (LO)	250.00 kW	400.00 hp
Rated power (HO)	200.00 kW	250.00 hp
Rated current (LO)	477.00 A	477.00 A
Rated current (HO)	370.00 A	361.00 A
Rated current (IN)	488.00 A	
Max. output current	644.00 A	
Pulse frequency	2 kHz	
Output frequency for vector control	0 200 Hz	
Output frequency for V/f control	0 550 Hz	

General tech. specifications		
Power factor λ	0.90 0.95	
Offset factor cos φ	0.99	
Efficiency η	0.98	
Sound pressure level (1m)	74 dB	
Power loss	6.180 kW	
Filter class (integrated)	RFI suppression filter for Category C2	
EMC category (with accessories)	Category C2	
Ambient conditions		
Class 2C2 passarding to IFC (0721.2		

Ambient conditions		
Standard board coating type	Class 3C3, according to IEC 60721-3-3: 2002	
Cooling	Air cooling using an integrated fan	
Cooling air requirement	0.210 m³/s (7.416 ft³/s)	
Installation altitude	1000 m (3280.84 ft)	
Ambient temperature		
Operation	-20 45 °C (-4 113 °F)	
Transport	-40 70 °C (-40 158 °F)	
Storage	-25 55 °C (-13 131 °F)	

Relative humidity

	95 % At 40 °C (104 °F), condensation
Max. operation	and icing not permissible

Overload capability

Low Overload (LO)

110% base load current IL for 60 s in a 300 s cycle time

High Overload (HO)

150% x base load current IH for 60 s within a 600 s cycle time



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Degree of protection IP20 / UL open type V/f linear / square-law / parar Size FSG Net weight 120 kg (264.56 lb) Width 305 mm (12.01 in) Height 999 mm (39.33 in) Depth 369 mm (14.53 in) Encoderless torque control Inputs / outputs Standard digital inputs Number 6 Switching level: 0→1 11 V Communication		
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Max. inrush current 15 mA Signal cable	PROFINET, EtherNet/IP	
Fail-safe digital inputs	Connections	
Number 1 Conductor cross-section	0.15 1.50 mm ² (AWG 24 AWG 16)	
Digital outputs Line side		
Number as relay changeover contact 2 Version	M10 screw	
Output (resistive load) DC 30 V, 5.0 A Conductor cross-section	35.00 185.00 mm ² (AWG 1 MCM 2 x 350)	
Number as transistor 0 Motor end		
Analog / digital inputs	M10 screw	
Number 2 (Differential input) Conductor cross-section	35.00 185.00 mm ² (AWG 1 MCM 2 x 350)	
Resolution 10 bit DC link (for braking resistor		
Switching threshold as digital input PE connection	M10 screw	
0→1 4 V Max. motor cable length	IVI I O SCIEW	
1→0		
Analog outputs	150 m (492.13 ft)	
5		

PTC/ KTY interface

Number

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^{\circ}\text{C}$

1 (Non-isolated output)



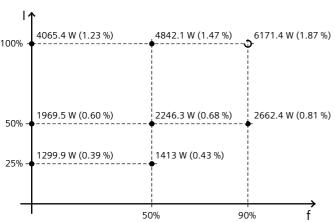
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Converter losses to EN 50598-2*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	-45.70 %



 $The \ percentage \ values \ show \ the \ losses \ in \ relation \ to \ the \ rated \ apparent \ power \ of \ the \ converter.$

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

Standards

Compliance with standards

UL, cUL, CE, C-Tick (RCM), EAC, KCC, SEMI F47, REACH

CE marking

EMC Directive 2004/108/EC, Low-Voltage Directive 2006/95/EC

^{*}converted values