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Data sheet for SINAMICS G120X

Article No. :

6SL3220-1YE16-0UB0



Figure similar

Client order no. :
Order no. :
Offer no. :
Remarks :

Rated data				
Input				
Number of phases	3 AC			
Line voltage	380 480 V +10 9	% -20 %		
Line frequency	47 63 Hz			
Rated voltage	400V IEC	480V NEC		
Rated current (LO)	5.50 A	4.60 A		
Rated current (HO)	3.60 A	3.00 A		
Output				
Number of phases	3 AC			
Rated voltage	400V IEC	480V NEC ¹⁾		
Rated power (LO)	2.20 kW	3.00 hp		
Rated power (HO)	1.50 kW	2.00 hp		
Rated current (LO)	5.90 A	4.80 A		
Rated current (HO)	4.10 A	3.40 A		
Rated current (IN)	6.10 A			
Max. output current	6.40 A			
Pulse frequency	4 kHz			
Output frequency for vector control	0 200 Hz			
Output frequency for V/f control	0 550 Hz			

Overload capability

Low Overload (LO)

110% base load current IL for 60 s in a 300 s cycle time

High Overload (HO)

150% x base load current IH for 60 s within a 600 s cycle time

General tech. specifications		
Power factor λ	0.70 0.85	
Offset factor $\cos \phi$	0.96	
Efficiency η	0.97	
Sound pressure level (1m)	55 dB	
Power loss ³⁾	0.091 kW	
Filter class (integrated)	Unfiltered	
EMC category (with accessories)	without	
Safety function "Safe Torque Off"	without SIRIUS device (e.g. via S7- 1500F)	
Communication		
G		

Communication

USS, Modbus RTU, BACnet MS/TP

ltem no. : Consignment no. : Project :

Inputs / outputs			
Standard digital inputs			
Number	6		
Switching level: $0 \rightarrow 1$	11 V		
Switching level: $1 \rightarrow 0$	5 V		
Max. inrush current	15 mA		
Fail-safe digital inputs			
Number	1		
Digital outputs			
Number as relay changeover contact	2		
Output (resistive load)	DC 30 V, 5.0 A		
Number as transistor	0		
Analog / digital inputs			
Number	2 (Differential input)		
Resolution	10 bit		
Switching threshold as digital input			
0 → 1	4 V		
1 → 0	1.6 V		
Analog outputs			
Number	1 (Non-isolated output)		
PTC/ KTY interface			
1 motor temperature sensor input, sen Thermo-Click, accuracy ±5 °C	nsors that can be connected PTC, KTY and		

Closed-loop control techniques		
V/f linear / square-law / parameterizable	Yes	
V/f with flux current control (FCC)	Yes	
V/f ECO linear / square-law	Yes	
Sensorless vector control	Yes	
Vector control, with sensor	No	
Encoderless torque control	No	
Torque control, with encoder	No	

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Ambient conditions			
Standard board coating type	Class 3C2, according to IEC 60721-3-3: 2002		
Cooling	Air cooling using an integrated fan		
Cooling air requirement	0.005 m³/s (0.177 ft³/s)		
Installation altitude	1,000 m (3,280.84 ft)		
Ambient temperature			
Operation	-20 45 °C (-4 113 °F)		
Transport	-40 70 °C (-40 158 °F)		
Storage	-25 55 °C (-13 131 °F)		
Relative humidity			
Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible		
Co	onnections		
Signal cable			
Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)		
Line side			
Version	screw-type terminal		
Conductor cross-section	1.50 2.50 mm² (AWG 16 AWG 14)		
Motor end			
Version	Screw-type terminals		
Conductor cross-section	1.50 2.50 mm² (AWG 16 AWG 14)		
DC link (for braking resistor)			
PE connection	On housing with M4 screw		
Max. motor cable length			
Shielded	150 m (492.13 ft)		
Unshielded	300 m (984.25 ft)		

3.2 kg (7.05 lb)	
232 mm (9.13 in)	
218 mm (8.58 in)	
UL, cUL, CE, C-Tick (RCM), EAC, KCC, SEMI F47, REACH	
EMC Directive 2004/108/EC, Low- Voltage Directive 2006/95/EC	
%)	
%)	
9	

The percentage values show the losses in relation to the rated apparent power of the converter.

90% **f**

50%

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

*converted values

¹⁾The output current and HP ratings are valid for the voltage range 440V-480V

³⁾ Typical value. More information can be found in the element group "Converter losses to IEC 61800-9-2" in this datasheet.