19-3478; Rev 4; 4/10

EVALUATION KIT

AVAILABLE

# 

## Dual, 256-Tap, Nonvolatile, SPI-Interface, **Linear-Taper Digital Potentiometers**

## **General Description**

The MAX5487/MAX5488/MAX5489 dual, linear-taper, digital potentiometers function as mechanical potentiometers with a simple 3-wire SPI<sup>™</sup>-compatible digital interface that programs the wipers to any one of 256 tap positions. These digital potentiometers feature a nonvolatile memory (EEPROM) to return the wipers to their previously stored positions upon power-up.

The MAX5487 has an end-to-end resistance of  $10k\Omega$ , while the MAX5488 and MAX5489 have resistances of  $50k\Omega$  and  $100k\Omega$ , respectively. These devices have a low 35ppm/°C end-to-end temperature coefficient, and operate from a single +2.7V to +5.25V supply.

The MAX5487/MAX5488/MAX5489 are available in 16-pin 3mm x 3mm x 0.8mm TQFN or 14-pin TSSOP packages. Each device is guaranteed over the extended -40°C to +85°C temperature range.

## **Applications**

LCD Screen Adjustment

Audio Volume Control

Mechanical Potentiometer Replacement

Low-Drift Programmable Filters

Low-Drift Programmable-Gain Amplifiers

## Features Wiper Position Stored in Nonvolatile Memory

- (EEPROM) and Recalled Upon Power-Up or **Recalled by an Interface Command**
- 3mm x 3mm x 0.8mm, 16-Pin TQFN or 14-Pin **TSSOP** Packages
- ♦ ±1 LSB INL, ±0.5 LSB DNL (Voltage-Divider Mode)
- 256 Tap Positions
- ♦ 35ppm/°C End-to-End Resistance Temperature Coefficient
- ♦ 5ppm/°C Ratiometric Temperature Coefficient
- $10k\Omega$ ,  $50k\Omega$ , and  $100k\Omega$  End-to-End Resistance Values
- SPI-Compatible Serial Interface
- Reliability 200,000 Wiper Store Cycles **50-Year Wiper Data Retention**
- +2.7V to +5.25V Single-Supply Operation

SPI is a trademark of Motorola, Inc.

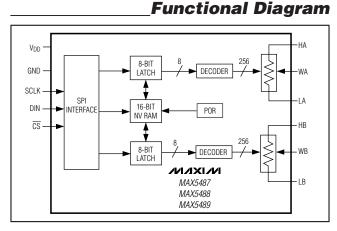
## **Ordering Information**

PART	ART TEMP RANGE PIN-F		PIN-PACKAGE END-TO-END RESISTANCE (kΩ)	
MAX5487ETE+	-40°C to +85°C	16 TQFN-EP*	10	ABR
MAX5487EUD+	-40°C to +85°C	14 TSSOP	10	—

\*EP = Exposed pad.

+Denotes a lead(Pb)-free/RoHS-compliant package.

Ordering Information continued at end of data sheet.

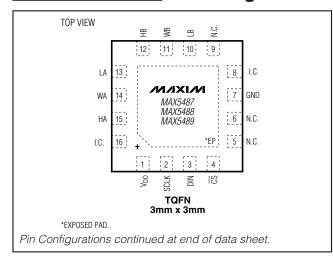


## M/XI/M

For pricing, delivery, and ordering information, please contact Maxim Direct at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.

## **Pin Configurations**

Maxim Integrated Products 1



#### **ABSOLUTE MAXIMUM RATINGS**

V <sub>DD</sub> to GND0	.3V to +6.0V	Continuous
All Other Pins		16-Pin T(
to GND0.3V to the lower of (V <sub>DD</sub> + 0.3)	V) and +6.0V	14-Pin TS
Maximum Continuous Current into H_, W_, and L_		Operating
MAX5487	±5.0mA	Junction Te
MAX5488	±1.3mA	Storage Te
MAX5489	±0.6mA	Lead Temp

Continuous Power Dissipation ( $T_A = +70^{\circ}C$ )	
16-Pin TQFN (derate 17.5mW/°C above +70°	°C)1398mW
14-Pin TSSOP (derate 9.1mW/°C above +70°	°C)727mW
Operating Temperature Range	40°C to +85°C
Junction Temperature	+150°C
Storage Temperature Range	60°C to +150°C
Lead Temperature (soldering, 10s)	+300°C
Soldering Temperature (reflow)	+260°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## DC ELECTRICAL CHARACTERISTICS

 $(V_{DD} = +2.7V \text{ to } +5.25V, V_H = V_{DD}, V_L = GND, T_A = -40^{\circ}C \text{ to } +85^{\circ}C, \text{ unless otherwise noted. Typical values are at } V_{DD} = +5.0V, T_A = +25^{\circ}C, \text{ unless otherwise noted.}$  (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	ТҮР	MAX	UNITS	
DC PERFORMANCE (Voltage-Div	ider Mode, Fi	gure 1)					
Resolution	Ν		256			Taps	
Integral Nonlinearity	INL	(Note 2)			±1	LSB	
Differential Nonlinearity	DNL	(Note 2)			±0.5	LSB	
Dual-Code Matching		Register A = register B			2	LSB	
End-to-End Resistor Tempco	TCR			35		ppm/°C	
Ratiometric Resistor Tempco				5		ppm/°C	
		MAX5487		3.5	6		
Full-Scale Error		MAX5488		-0.6	+1.2	LSB	
		MAX5489		-0.3	+1.2	1	
		MAX5487		3.5	6		
Zero-Scale Error		MAX5488		-0.6	1.5	LSB	
		MAX5489		0.3	1		
DC PERFORMANCE (Variable-Re	sistor Mode,	Figure 1)					
Resolution			256			Taps	
Integral Nonlinearity (Note 3)		$V_{DD} = 5.0V$			±1.5	LSB	
integral Noninearity (Note 3)		$V_{DD} = 3.0V$			±3	LOD	
Differential Neplinearity (Note 2)		$V_{DD} = 5.0V$			±1	LSB	
Differential Nonlinearity (Note 3)		$V_{DD} = 3.0V$			±1	LOD	
DC PERFORMANCE (Resistor Ch	aracteristics						
Winer Desistance (Note 4)	Dere	$V_{DD} = 5.0V$		200	350	Ω	
Wiper Resistance (Note 4)	Rw	V <sub>DD</sub> = 3.0V		325	675		
Wiper Capacitance	Cw			50		рF	
		MAX5487	7.5	10	12.5		
End-to-End Resistance	R <sub>HL</sub>	MAX5488	37.5	50	62.5	kΩ	
		MAX5489	75	100	125		

## DC ELECTRICAL CHARACTERISTICS (continued)

 $(V_{DD} = +2.7V \text{ to } +5.25V, V_H = V_{DD}, V_L = GND, T_A = -40^{\circ}C \text{ to } +85^{\circ}C, \text{ unless otherwise noted. Typical values are at } V_{DD} = +5.0V, T_A = +25^{\circ}C, \text{ unless otherwise noted.}) (Note 1)$ 

PARAMETER	SYMBOL	CON	MIN	ΤΥΡ	MAX	UNITS		
DIGITAL INPUTS								
		$V_{DD} = 3.6V$ to 5.25V		2.4			]	
Input High Voltage (Note 5)	VIH	Vpp = 2.7V to 3.6V		0.7 x			V	
		VDD = 2.7 V 10 3.6 V		VDD				
Input Low Voltage	VIL	$V_{DD} = 2.7V$ to $5.25V$	(Note 5)			0.8	V	
Input Leakage Current	lin					±1.0	μA	
Input Capacitance	CIN				5.0		pF	
AC PERFORMANCE		-					<u> </u>	
Crosstalk		f <sub>H</sub> _ = 1kHz, L_ = GN (Note 6)	D, measurement at W_		-90		dB	
			MAX5487		350			
-3dB Bandwidth	BW	Wiper at midscale $C_{W_}$ = 10pF	MAX5488		90		kHz	
			MAX5489		45		1	
Total Harmonic Distortion	THD	V <sub>H</sub> _ = 1V <sub>RMS</sub> at 1kH measurement at W_		0.02		%		
TIMING CHARACTERISTICS (Anal	og)							
			MAX5487		0.5			
Wiper-Settling Time	ts	Code 0 to 127	MAX5488		0.75		μs	
		(Note 7)	MAX5489		1.5			
TIMING CHARACTERISTICS (Digit	al, Figure 2,	Note 8)						
SCLK Frequency						5	MHz	
SCLK Clock Period	tCP			200			ns	
SCLK Pulse-Width High	tСН			80			ns	
SCLK Pulse-Width Low	tCL			80			ns	
CS Fall to SCLK Rise Setup	tcss			80			ns	
SCLK Rise to $\overline{CS}$ Rise Hold	tCSH			0			ns	
DIN to SCLK Setup	tDS			50			ns	
DIN Hold after SCLK	tDH			0			ns	
SCLK Rise to $\overline{CS}$ Fall Delay	tCS0			20			ns	
CS Rise to SCLK Rise Hold	tCS1			80			ns	
CS Pulse-Width High	tcsw			200			ns	
Write NV Register Busy Time	tBUSY					12	ms	
Read NV Register Access Time	tacc					1	μs	
Write Wiper Register to Output Delay	two					1	μs	
NONVOLATILE MEMORY RELIABI	LITY							
Data Retention		$T_A = +85^{\circ}C$			50		Years	
Endurance		$T_A = +25^{\circ}C$			200,000		Store	
Endurance		T <sub>A</sub> = +85°C				50,000		

#### DC ELECTRICAL CHARACTERISTICS (continued)

 $(V_{DD} = +2.7V \text{ to } +5.25V, V_H = V_{DD}, V_L = GND, T_A = -40^{\circ}C \text{ to } +85^{\circ}C, \text{ unless otherwise noted. Typical values are at } V_{DD} = +5.0V, T_A = +25^{\circ}C, \text{ unless otherwise noted.}$  (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
POWER SUPPLIES						
Power-Supply Voltage	V <sub>DD</sub>		2.70		5.25	V
Supply Current	I <sub>DD</sub>	During write cycle only, digital inputs = V <sub>DD</sub> or GND			400	μA
Standby Current		Digital inputs = $V_{DD}$ or GND, $T_A = +25^{\circ}C$		0.5	1	μA

**Note 1:** All devices are production tested at  $T_A = +85^{\circ}C$  and are guaranteed by design and characterization for  $-40^{\circ}C < T_A < +85^{\circ}C$ .

Note 2: DNL and INL are measured with the potentiometer configured as a voltage-divider with H\_ = V<sub>DD</sub> and L\_ = 0. The wiper terminal is unloaded and measured with an ideal voltmeter.

**Note 3:** DNL and INL are measured with the potentiometer configured as a variable resistor. H\_ is unconnected and L\_ = 0. For V<sub>DD</sub> = +5V, the wiper terminal is driven with a source current of 400µA for the 10k $\Omega$  configuration, 80µA for the 50k $\Omega$  configuration, and 40µA for the 100k $\Omega$  configuration. For V<sub>DD</sub> = +3V, the wiper terminal is driven with a source current of 200µA for the 10k $\Omega$  configuration, 40µA for the 50k $\Omega$  configuration, and 20µA for the 100k $\Omega$  configuration.

Note 4: The wiper resistance is the worst value measured by injecting the currents given in Note 3 into W\_ with L\_ = GND.  $R_W = (V_W - V_H) / I_W$ .

**Note 5:** The device draws higher supply current when the digital inputs are driven with voltages between (V<sub>DD</sub> - 0.5V) and (GND + 0.5V). See Supply Current vs. Digital Input Voltage in the *Typical Operating Characteristics* section.

Note 6: Wiper at midscale with a 10pF load.

- **Note 7:** Wiper-settling time is the worst-case 0-to-50% rise time, measured between tap 0 and tap 127. H\_ = V<sub>DD</sub>, L\_ = GND, and the wiper terminal is unloaded and measured with a 10pF oscilloscope probe (see Tap-to-Tap Switching Transient in the *Typical Operating Characteristics* section).
- Note 8: Digital timing is guaranteed by design and characterization, and is not production tested.

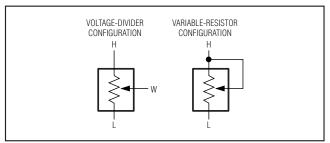
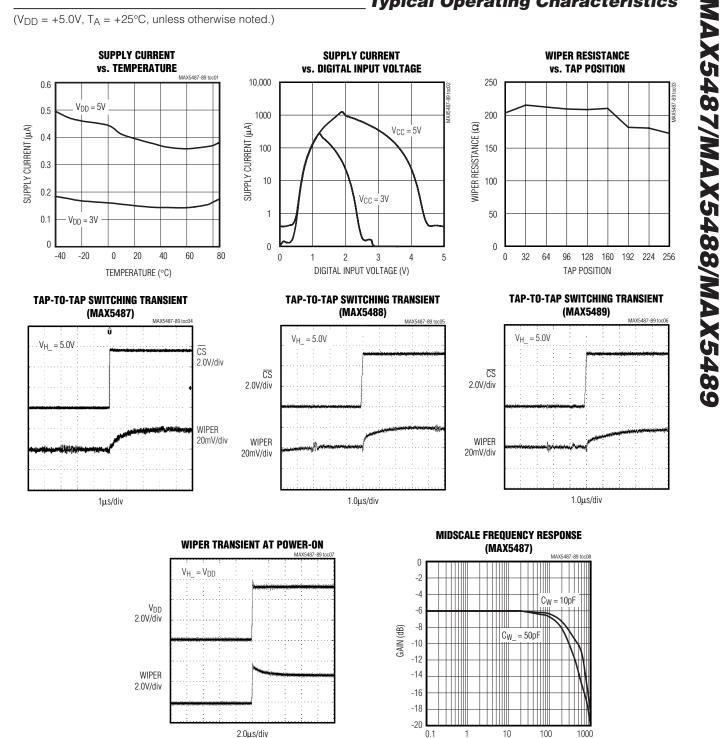


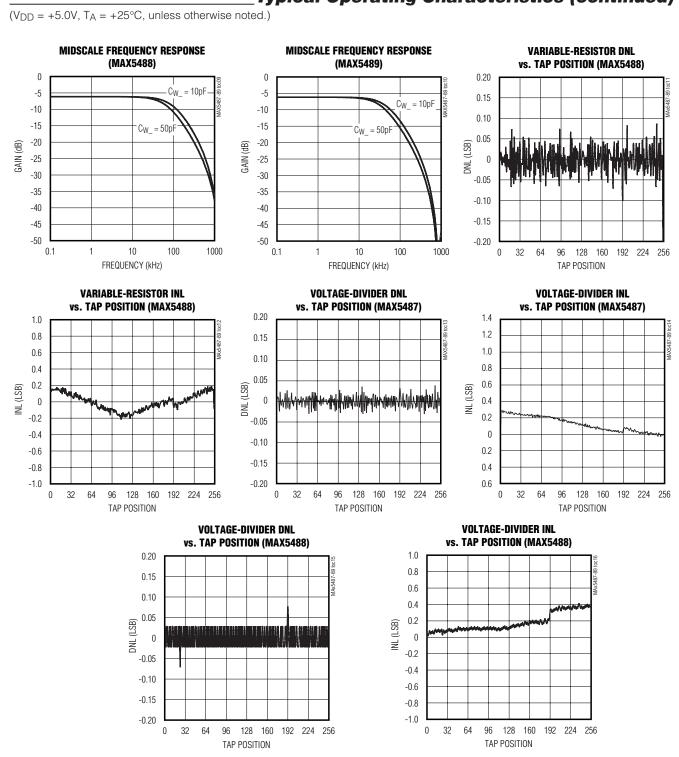
Figure 1. Voltage-Divider/Variable-Resistor Configurations



## **Typical Operating Characteristics**

FREQUENCY (kHz)

MXXIM

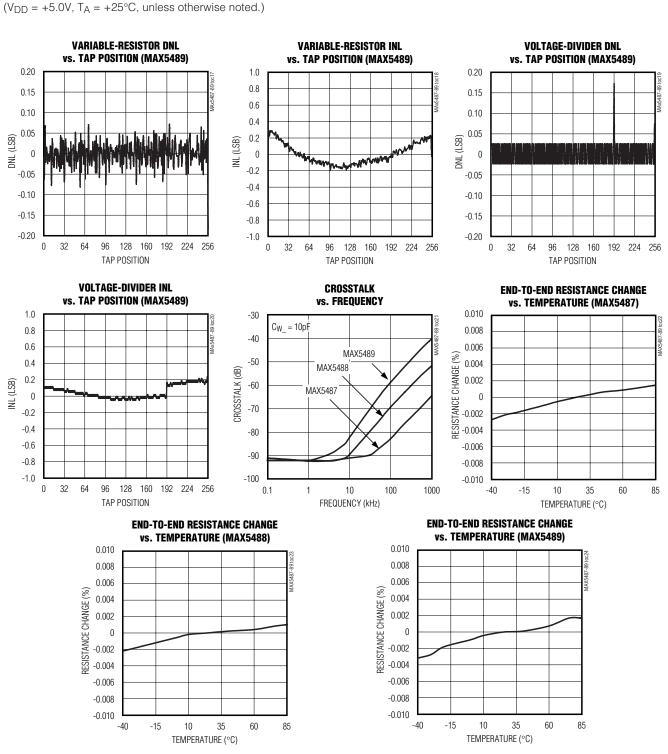


**Typical Operating Characteristics (continued)** 

MIXIM

MAX5487/MAX5488/MAX5489

**Typical Operating Characteristics (continued)** 



MAX5487/MAX5488/MAX5489

#### **Pin Description**

		NAME	FUNCTION
TQFN	TSSOP	NAME	FUNCTION
1	14	V <sub>DD</sub>	Power Supply. Bypass $V_{DD}$ to GND with a 0.1 $\mu$ F capacitor as close to the device as possible.
2	13	SCLK	Serial-Interface Clock Input
3	12	DIN	Serial-Interface Data Input
4	11	CS	Active-Low Chip-Select Digital Input
5, 6, 9	7, 9, 10	N.C.	No Connection. Not internally connected.
7	8	GND	Ground
8, 16	_	I.C.	Internally connected to EP. Leave unconnected.
10	6	LB	Low Terminal of Resistor B. The voltage at L can be greater than or less than the voltage at H. Current can flow into or out of L.
11	5	WB	Wiper Terminal of Resistor B
12	4	HB	High Terminal of Resistor B. The voltage at H can be greater than or less than the voltage at L. Current can flow into or out of H.
13	3	LA	Low Terminal of Resistor A. The voltage at L can be greater than or less than the voltage at H. Current can flow into or out of L.
14	2	WA	Wiper Terminal of Resistor A
15	1	HA	High Terminal of Resistor A. The voltage at H can be greater than or less than the voltage at L. Current can flow into or out of H.
		EP	Exposed Pad (TQFN only). Internally connected to pins 8 and 16. Leave unconnected.

## **Detailed Description**

The MAX5487/MAX5488/MAX5489 contain two resistor arrays, with 255 resistive elements each. The MAX5487 has an end-to-end resistance of 10k $\Omega$ , while the MAX5488 and MAX5489 have resistances of 50k $\Omega$  and 100k $\Omega$ , respectively. The MAX5487/MAX5488/MAX5489 allow access to the high, low, and wiper terminals on both potentiometers for a standard voltage-divider configuration. Connect the wiper to the high terminal, and connect the low terminal to ground, to make the device a variable resistor (see Figure 1).

A simple 3-wire serial interface programs either wiper directly to any of the 256 tap points. The nonvolatile memory stores the wiper position prior to power-down and recalls the wiper to the same point upon power-up or by using an interface command (see Table 1). The nonvolatile memory is guaranteed for 200,000 wiper store cycles and 50 years for wiper data retention.

#### **SPI Digital Interface**

The MAX5487/MAX5488/MAX5489 use a 3-wire SPIcompatible serial data interface (Figures 2 and 3). This write-only interface contains three inputs: chip-select  $(\overline{CS})$ , data clock (SCLK), and data in (DIN). Drive  $\overline{CS}$  low to enable the serial interface and clock data synchronously into the shift register on each SCLK rising edge.

The WRITE commands (C1, C0 = 00 or 01) require 16 clock cycles to clock in the command, address, and data (Figure 3a). The COPY commands (C1, C0 = 10, 11) can use either eight clock cycles to transfer only command and address bits (Figure 3b) or 16 clock cycles, with the device disregarding 8 data bits (Figure 3a).

After loading data into the shift register, drive  $\overline{CS}$  high to latch the data into the appropriate potentiometer control register and disable the serial interface. Keep  $\overline{CS}$  low during the entire serial data stream to avoid corruption of the data.

#### Digital-Interface Format

The data format consists of three elements: command bits, address bits, and data bits (see Table 1 and Figure 3). The command bits (C1 and C0) indicate the action to be taken such as changing or storing the wiper position. The address bits (A1 and A0) specify which potentiometer the command affects and the 8 data bits (D7 to D0) specify the wiper position.



#### Table 1. Register Map

CLOCK EDGE	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
		_	C1	C0			A1	A0	D7	D6	D5	D4	D3	D2	D1	D0
Write Wiper Register A	0	0	0	0	0	0	0	1	D7	D6	D5	D4	D3	D2	D1	D0
Write Wiper Register B	0	0	0	0	0	0	1	0	D7	D6	D5	D4	D3	D2	D1	D0
Write NV Register A	0	0	0	1	0	0	0	1	D7	D6	D5	D4	D3	D2	D1	D0
Write NV Register B	0	0	0	1	0	0	1	0	D7	D6	D5	D4	D3	D2	D1	D0
Copy Wiper Register A to NV Register A	0	0	1	0	0	0	0	1	_	_	_	_	_			_
Copy Wiper Register B to NV Register B	0	0	1	0	0	0	1	0	_	_	_	_	_			_
Copy Both Wiper Registers to NV Registers	0	0	1	0	0	0	1	1	_	_	_	_	_	_	_	_
Copy NV Register A to Wiper Register A	0	0	1	1	0	0	0	1	_	_	_	_	_			_
Copy NV Register B to Wiper Register B	0	0	1	1	0	0	1	0	_	_	_	_	_	_	_	_
Copy Both NV Registers to Wiper Registers	0	0	1	1	0	0	1	1	_	_	_	_	_	_		_

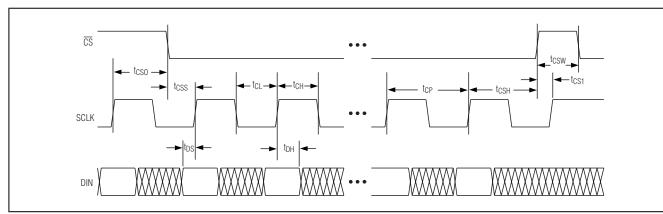


Figure 2. Timing Diagram

#### Write-Wiper Register (Command 00)

Data written to the write-wiper registers (C1, C0 = 00) controls the wiper positions. The 8 data bits (D7 to D0) indicate the position of the wiper. For example, if DIN = 0000 0000, the wiper moves to the position closest to L\_. If DIN = 1111 1111, the wiper moves closest to H\_.

This command writes data to the volatile RAM, leaving the NV registers unchanged. When the device powers up, the data stored in the NV registers transfers to the volatile wiper register, moving the wiper to the stored position.

#### Write-NV Register (Command 01)

This command (C1, C0 = 01) stores the position of the wipers to the NV registers for use at power-up. Alternatively, the "copy wiper register to NV register" command can be used to store the position of the wipers to the NV registers. Writing to the NV registers does not affect the position of the wipers.

**Copy Wiper Register to NV Register (Command 10)** This command (C1, C0 = 10) stores the current position of the wiper to the NV register, for use at power-up. This command may affect one potentiometer at a time,



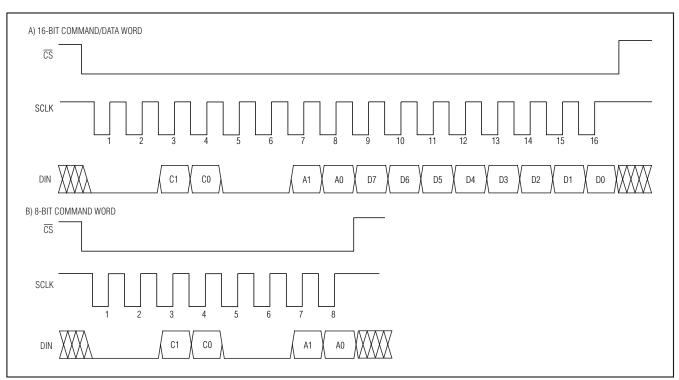


Figure 3. Digital-Interface Format

or both simultaneously, depending on the state of A1 and A0. Alternatively, the "write NV register" command can be used to store the current position of the wiper to the NV register.

**Copy NV Register to Wiper Register (Command 11)** This command (C1, C0 = 11) restores the wiper position to the previously stored position in the NV register. This command may affect one potentiometer at a time, or both simultaneously, depending on the state of A1 and A0.

#### **Nonvolatile Memory**

The internal EEPROM consists of a nonvolatile register that retains the last stored value prior to power-down. The nonvolatile register is programmed to midscale at the factory. The nonvolatile memory is guaranteed for 200,000 wiper write cycles and 50 years for wiper data retention.

#### **Power-Up**

Upon power-up, the MAX5487/MAX5488/MAX5489 load the data stored in the nonvolatile wiper register into the volatile memory register, updating the wiper position with the data stored in the nonvolatile wiper register. This initialization period takes 5µs.

#### Standby

The MAX5487/MAX5488/MAX5489 feature a low-power standby mode. When the device is not being programmed, it enters into standby mode and supply current drops to  $0.5\mu$ A (typ).

#### Applications Information

The MAX5487/MAX5488/MAX5489 are ideal for circuits requiring digitally controlled adjustable resistance, such as LCD contrast control (where voltage biasing adjusts the display contrast), or for programmable filters with adjustable gain and/or cutoff frequency.

#### **Positive LCD Bias Control**

Figures 4 and 5 show an application where the MAX5487/MAX5488/MAX5489 provide an adjustable, positive LCD-bias voltage. The op amp provides buffering and gain to the resistor-divider network made by the potentiometer (Figure 4) or by a fixed resistor and a variable resistor (Figure 5).

#### **Programmable Filter**

Figure 6 shows the MAX5487/MAX5488/MAX5489 in a 1st-order programmable-filter application. Adjust the gain of the filter with R<sub>2</sub>, and set the cutoff frequency with R<sub>3</sub>.



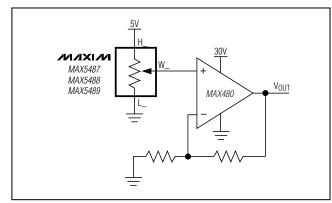


Figure 4. Positive LCD-Bias Control Using a Voltage-Divider

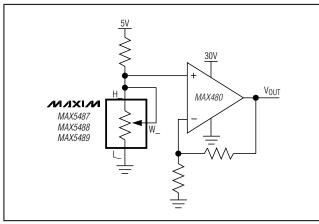


Figure 5. Positive LCD-Bias Control Using a Variable Resistor

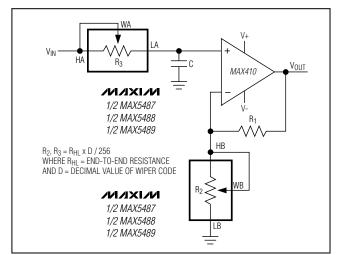


Figure 6. Programmable Filter



Use the following equations to calculate the gain (A) and the -3dB cutoff frequency (fc):

$$A = 1 + \frac{R_1}{R_2}$$
$$f_C = \frac{1}{2\pi \times R_3 \times C}$$

#### Adjustable Voltage Reference

Figure 7 shows the MAX5487/MAX5488/MAX5489 used as the feedback resistors in multiple adjustable voltage-reference applications. Independently adjust the output voltages of the MAX6160s from 1.23V to  $V_{IN}$  - 0.2V by changing the wiper positions of the MAX5487/MAX5488/MAX5489.

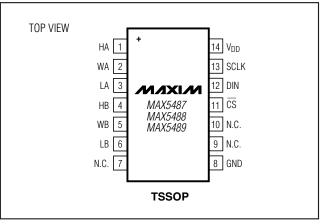
#### **Offset Voltage and Gain Adjustment**

Connect the high and low terminals of one potentiometer of a MAX5487/MAX5488/MAX5489 to the NULL inputs of a MAX410, and connect the wiper to the op amp's positive supply to nullify the offset voltage over the operating temperature range. Install the other potentiometer in the feedback path to adjust the gain of the MAX410 (see Figure 8).

#### Chip Information

PROCESS: BICMOS

## Pin Configurations (continued)



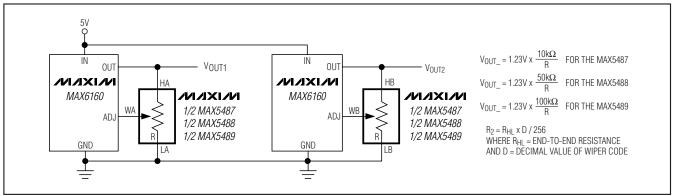


Figure 7. Adjustable Voltage Reference

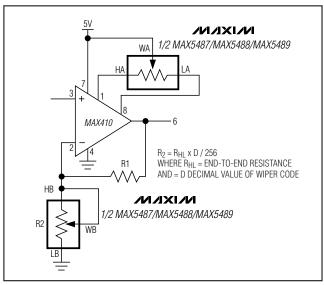


Figure 8. Offset Voltage and Gain Adjustment

#### **Package Information**

For the latest package outline information and land patterns, go to **www.maxim-ic.com/packages**. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

PACKAGE TYPE	PACKAGE CODE	OUTLINE NO.	LAND PATTERN NO.
16 TQFN-EP	T1633F+3	<u>21-0136</u>	<u>90-0033</u>
14 TSSOP	U14+1	<u>21-0066</u>	<u>90-0113</u>

## Ordering Information (continued)

PART	TEMP RANGE	PIN-PACKAGE END-TO-END RESISTANCE (kΩ)		TOP MARK
MAX5488ETE+	-40°C to +85°C	16 TQFN-EP*	50	ABS
MAX5488EUD+	-40°C to +85°C	14 TSSOP	50	—
MAX5489ETE+	-40°C to +85°C	16 TQFN-EP*	100	ABT
MAX5489EUD+	-40°C to +85°C	14 TSSOP	100	—
MAX5489ETE/V+	-40°C to +85°C	16 TQFN-EP*	100	AIE

\*EP = Exposed pad.

+Denotes a lead(Pb)-free/RoHS-compliant package.

*N* denotes an automotive qualified part.

## **Revision History**

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
3	1/07	—	1, 8, 12, 15
4	4/10	Updated <i>Ordering Information</i> (added lead-free packaging and automotive qualified part, released TSSOP package), and updated <i>Absolute Maximum Ratings</i>	1, 2, 12

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